

# Depth Separation with Multilayer Mean-Field Networks

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## Background: Depth Separation

- Why deeper networks are more powerful than shallow ones?
- Eldan & Shamir, 2016; Telgarsky, 2016; Daniely, 2017 ...
  - There exists some functions that are **approximable** by deep networks by not by shallow ones.

### Theorem (Theorem 5 of (Safran et al., 2019))

*There exists a **spherically symmetric** input distribution  $\mathcal{D}$  s.t. **no** 2-layer networks with width  $\text{poly}(d/\varepsilon)$  can **approximate** the target function  $f_*(\mathbf{x}) = \text{ReLU}(1 - \|\mathbf{x}\|)$ ,  $\mathbf{x} \in \mathbb{R}^d$  to  $\text{MSE} \leq \varepsilon$ , which can be easily achieved by a 3-layer network.*

- **Question:** Is this separation algorithmic?
  - Can GD + a 3-layer network **learn** this function?

# Our Results

## Theorem (Informal version of Theorem 2.1)

*Same setting as in (Safran et al., 2019). There exists a 3-layer network s.t. for any input dim  $d$  and target  $\varepsilon$ , we can choose layer widths  $m_1 = \text{poly}(d/\varepsilon)$ ,  $m_2 = \Theta(1)$  so that, with probability  $\geq 1 - 1/\text{poly}(d/\varepsilon)$  over random initialization, running a simple variant of GF will reduce the MSE to  $\varepsilon$  within  $\text{poly}(d/\varepsilon)$  time.*

- Main techniques/proof strategy:
  - A simple framework for multilayer mean-field networks,
    - where we can reason about multilayer networks with potentially infinitely many neurons.
  - Characterizing the infinite-width mean-field dynamics.
  - $\text{poly}(d/\varepsilon)$ -width discretization under symmetry.
    - In general, tracking the mean-field trajectory requires  $\exp(d)$  neurons because of the compounding error.
- Comparison with (Safran & Lee, 2022): Different target/learner/techniques.

# Outline

- 1 2-layer mean-field networks and our extension.
- 2 The infinite-width dynamics.
- 3  $\text{poly}(d)$ -width discretization under symmetry.

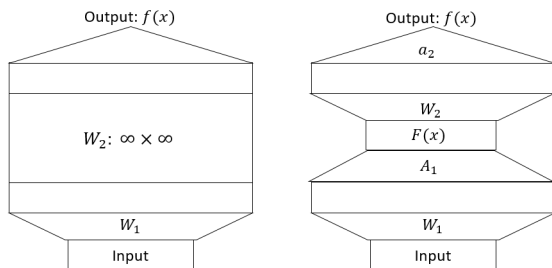
# Background: Mean-Field Networks

- Let  $\mu$  be the empirical distribution of  $\{\mathbf{w}_k\}_{k=1}^m$ .

$$f(\mathbf{x}; \mathbf{W}) = \frac{1}{m} \sum_{k=1}^m \phi(\mathbf{x}; \mathbf{w}_k) = \int \phi(\mathbf{x}; \mathbf{w}) d\mu(\mathbf{w}) =: f(\mathbf{x}; \mu).$$

- Allowing  $\mu$  to be any (nice) distribution; Let  $m \rightarrow \infty$ .
  - $\Rightarrow$  2-layer mean-field networks.
- Question: How to generalize this to  $\geq 3$  layers (without introducing too much math)?

# Our Results: Multilayer Mean-Field Networks



- Main challenge: as width  $\rightarrow \infty$ ,  $W_2$  becomes an  $\infty \times \infty$  matrix.
  - Existing workarounds: distribution over functions, introducing an indexing set, ...
- Our solution: project the intermediate representations to  $D$ -dimensional vectors  $F(\mathbf{x})$  ( $D < \infty$ ).
  - Reminiscent of the bottleneck structure from ResNets;
  - Much easier to use;
  - Retain the permutation invariant property of the neurons.

# The Infinite-Width Dynamics

- **Learner network:** (We choose the bottleneck dimension  $D$  to be 1.)

$$\text{First layer: } F(\mathbf{x}; \mu_1) = \mathbb{E}_{\mathbf{w}_1 \sim \mu_1} \|\mathbf{w}_1\| \text{ReLU}(\mathbf{w}_1 \cdot \mathbf{x}),$$

$$\text{Second layer: } f(\mathbf{x}; \mu_2, \mu_1) = \mathbb{E}_{(w_2, b_2) \sim \mu_2} \text{ReLU}(w_2 F(\mathbf{x}; \mu_1) + b_2).$$

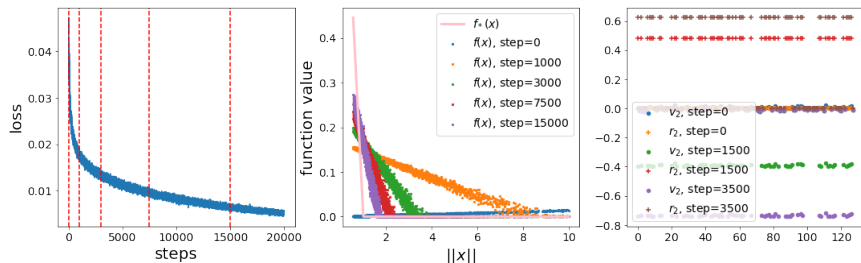
- **Lemma:**  $\mu_{1,t}$  spherically symmetric  $\Rightarrow F(\mathbf{x}; \mu_{1,t}) = \alpha_t \|\mathbf{x}\|$ ,  $\alpha_t \in \mathbb{R}_+$ , where  $\alpha_t$  depends only on  $\mathbb{E}_{\mathbf{w}_1} \|\mathbf{w}_1\|^2$ .

# The Infinite-Width Dynamics

- **Lemma:**  $\mu_{1,t}$  spherically symmetric  $\Rightarrow F(\mathbf{x}; \mu_{1,t}) = \alpha_t \|\mathbf{x}\|$ ,  $\alpha_t \in \mathbb{R}_+$ .
- **Facts/Claims:**
  - ① The (infinite-width) initial distribution  $\mu_{1,0}$ , input distribution  $\mathcal{D}$ , and target function  $f_*$  are all spherically symmetric.
  - ② By symmetry,  $\mu_{1,t}$  remains spherically symmetric for all  $t \geq 0$ .
  - ③ The dynamics of  $\alpha_t$  depend on  $\mu_{1,t}$  only through  $\alpha_t$ .
- $\Rightarrow$  The infinite-width dynamics of the first layer are simple! Only need to look at a single real number  $\alpha_t$ .
- **Claim:** GF + the infinite-width network will fit the target function.



# Finite-Width Simulation



- $f$  is always approximately spherically symmetric.
- $f$  eventually fits the target function  $f_*(\mathbf{x}) = \text{ReLU}(1 - \|\mathbf{x}\|)$ .
- (The second layer behaves like a single neuron ( $\bar{w}_2, \bar{b}_2$ ).
- **Observation:** The finite-width network closely tracks the infinite-width one (at least empirical).

## poly( $d$ )-width discretization

- **Main challenge:** Errors can compound; the discretization error can potentially grow exponentially fast; need  $\exp(d)$  neurons to make the initial error exponentially small.
- **Observation:** The infinite-width network is a symmetrization of the finite-width network.
  - Any  $\mu_{1,t}$  (not necessarily spherically symmetric),

$$\tilde{F}(\mathbf{x}; \mu_{1,t}) := \mathbb{E}_{\mathbf{x}' \in \|\mathbf{x}\| \mathbb{S}^{d-1}} F(\mathbf{x}') = \alpha_t \|\mathbf{x}\|.$$

- **Decomposition of the MSE loss:**

$$\mathcal{L} = \frac{1}{2} \mathbb{E}_{\mathbf{x}} (f_*(\mathbf{x}) - \tilde{f}(\mathbf{x}))^2 + \frac{1}{2} \mathbb{E}_{\mathbf{x}} (f(\mathbf{x}) - \tilde{f}(\mathbf{x}))^2 - \mathbb{E}_{\mathbf{x}} (f_*(\mathbf{x}) - \tilde{f}(\mathbf{x})) (f(\mathbf{x}) - \tilde{f}(\mathbf{x}))$$

- Error of the infinite-width network
- Discretization error:  $\approx (\bar{w}_2^2/2) \mathbb{E}_{\mathbf{x}} (F(\mathbf{x}) - \tilde{F}(\mathbf{x}))^2$
- = 0 as a result of symmetrization

## poly( $d$ )-width discretization (continued)

- Decomposition of the MSE loss:

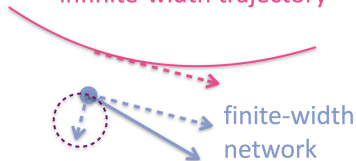
$$\mathcal{L} \approx \frac{1}{2} \mathbb{E}_{\mathbf{x}} (f_*(\mathbf{x}) - \tilde{f}(\mathbf{x}))^2 + \frac{\bar{w}_2^2}{2} \mathbb{E}_{\mathbf{x}} (F(\mathbf{x}) - \tilde{F}(\mathbf{x}))^2.$$

- **Claim:** The gradients of these two terms do not interfere with each other.
  - $\Rightarrow$  The second term ensures the discretization error does not grow. (No compounding errors!)
  - $\Rightarrow$  Only need the initial error to be inversely polynomially small. (Can be achieved using poly( $d$ ) neurons.)

# poly( $d$ )-width discretization (the operational aspect)

## The General Case

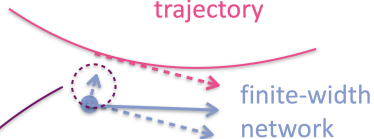
infinite-width trajectory



Compounding errors!

## Under Symmetry

infinite-width/symmetrized trajectory



Pointing towards the infinite-width trajectory.  
No compounding errors!

Q: How to show this?

A: Taylor expand the dynamics around the infinite-width trajectory.  
Look at the first-order terms.

# Conclusion

- Poster: #134, 4:30 PM - 6:30 PM (today)
- Takeaways:
  - The 3-layer vs 2-layer separation is algorithmic.
  - With symmetry, the infinite-width dynamics can be much simpler than the finite-width ones.
  - With symmetry,  $\text{poly}(d)$ -width discretization is possible.
- Future directions:
  - General second-layer function.
  - Subspace version:  $f_*(\mathbf{x}) = \text{ReLU}(1 - \|\mathbf{A}^\top \mathbf{x}\|)$  where  $\mathbf{A} \in \mathbb{R}^{d \times r}$  is column orthogonal.
  - More generic  $\text{poly}(d)$ -width discretization.